

A Quest for Short Identities

Which questions does automata theory ask algebra over and over again (but gets no answers so far)?

Mikhail Volkov

Ural Federal University, Ekaterinburg, Russia



GAIA, July 19, 2013

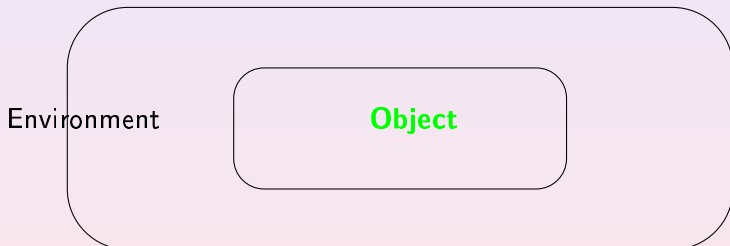
Finite Automata

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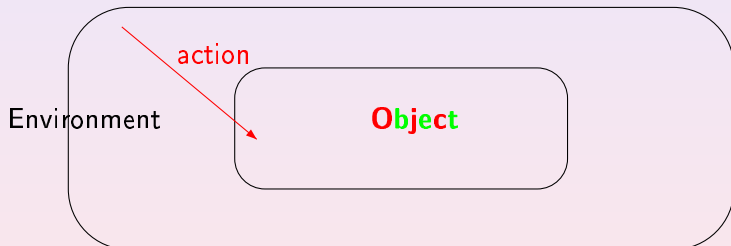
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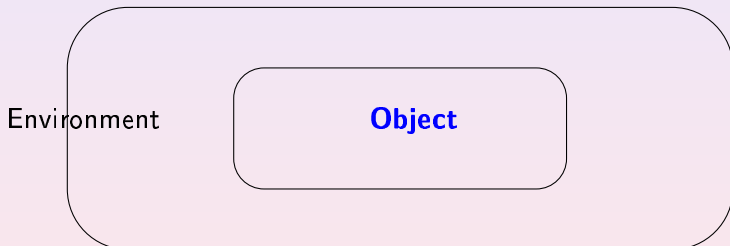
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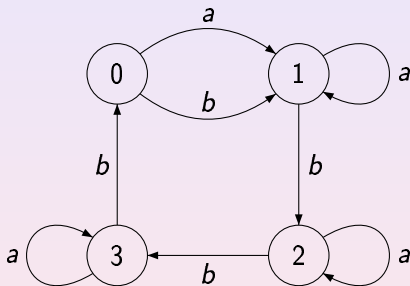
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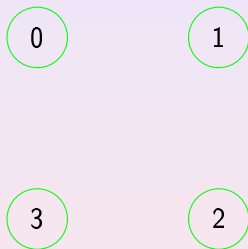
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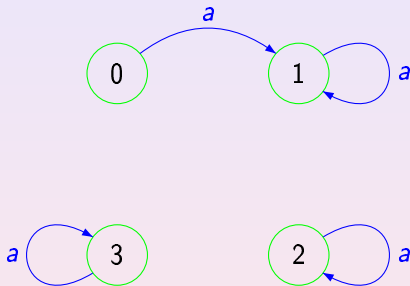


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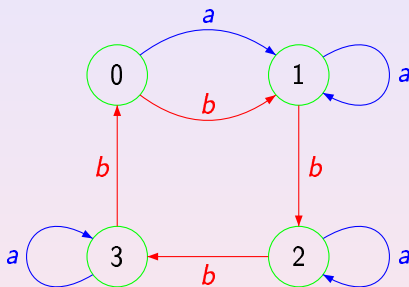
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Here one sees 4 **states** called 0,1,2,3, an action called *a* and another action called *b*.

Terminology and Notation

We consider complete deterministic finite automata (DFAs):

$$\mathcal{A} = \langle Q, \Sigma, \delta \rangle.$$

Here

- Q is the state set;
- Σ is the input alphabet;
- $\delta : Q \times \Sigma \rightarrow Q$ is the transition function.

Σ^* stands for the set of all words over Σ including the empty word.

The function δ uniquely extends to a function $Q \times \Sigma^* \rightarrow Q$ still denoted by δ .

To simplify notation we write $q \cdot w$ for $\delta(q, w)$.

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Synchronizing Automata

A DFA $\mathcal{A} = \langle Q, \Sigma, \delta \rangle$ is called **synchronizing** if there exists a word $w \in \Sigma^*$ whose action resets \mathcal{A} , that is, leaves \mathcal{A} in one particular state no matter at which state in Q the word w was applied:
 $q \cdot w = q' \cdot w$ for all $q, q' \in Q$.

Any word w with this property is a **reset word** for \mathcal{A} .

Other names:

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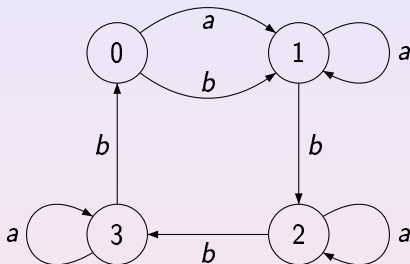
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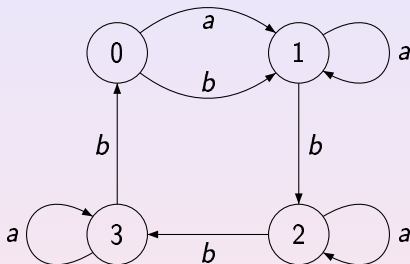
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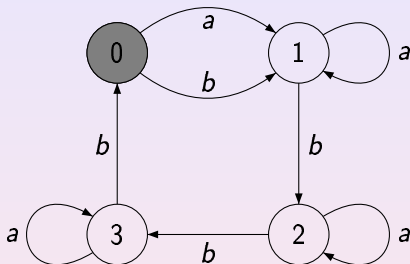
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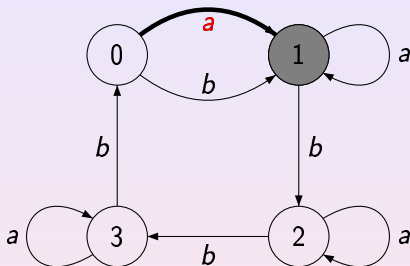
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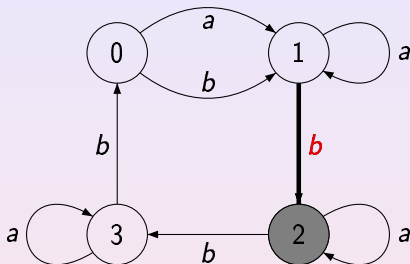
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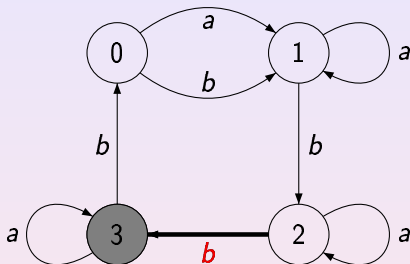
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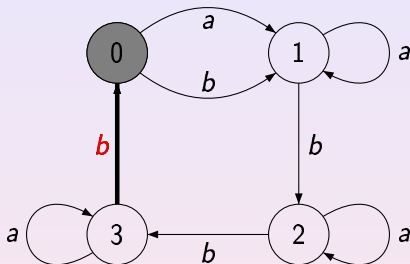
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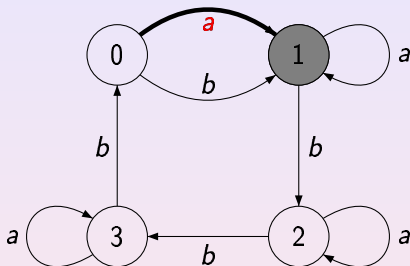
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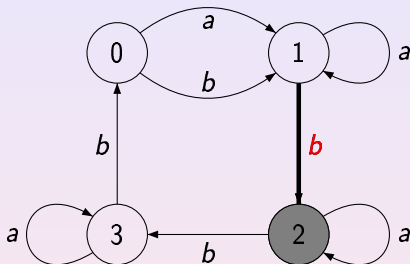
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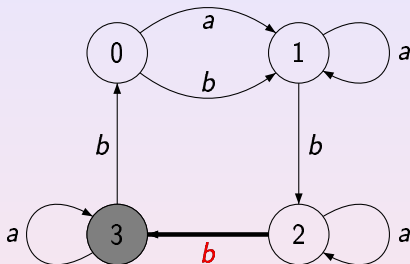
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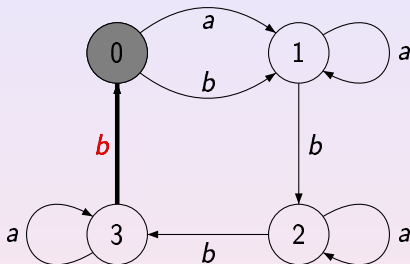
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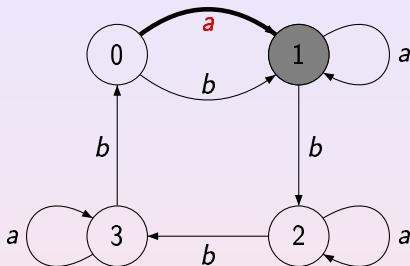
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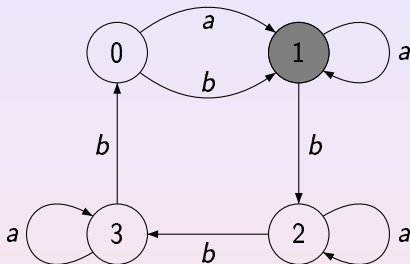


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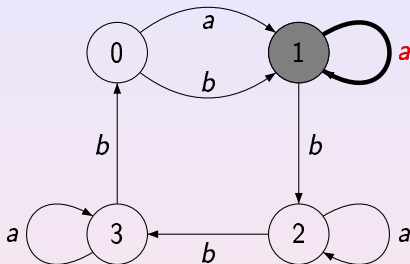


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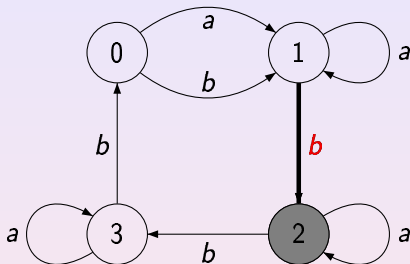


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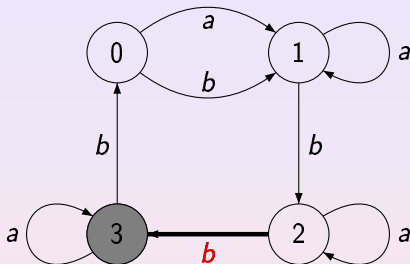


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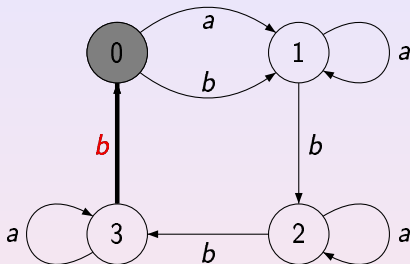


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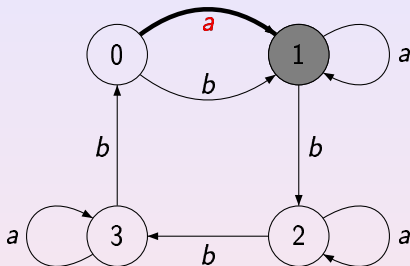


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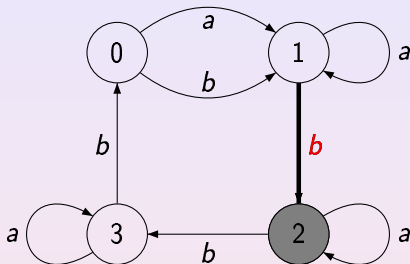


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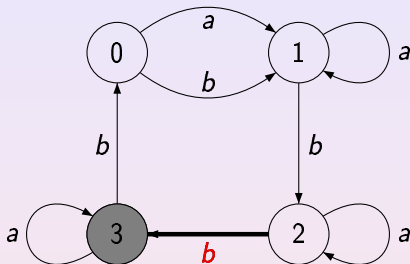


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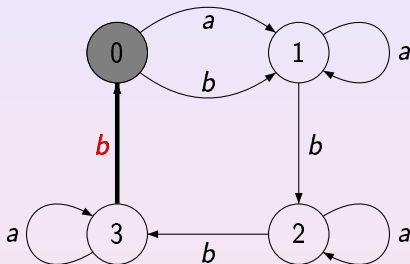


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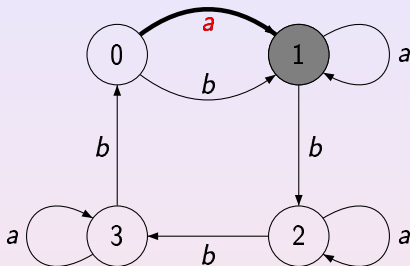


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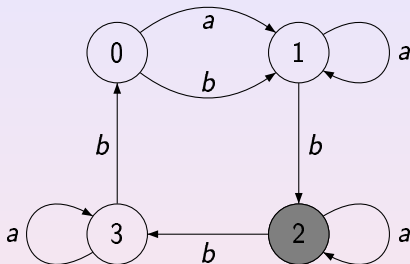
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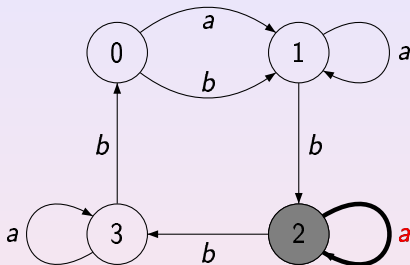
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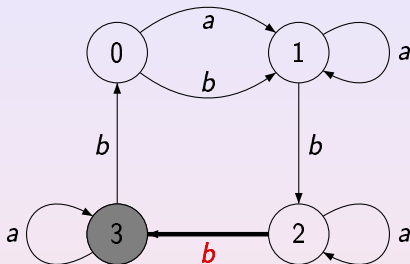


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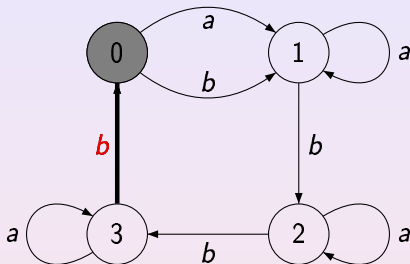
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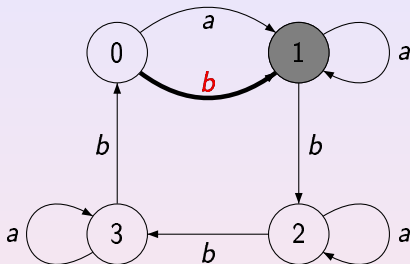
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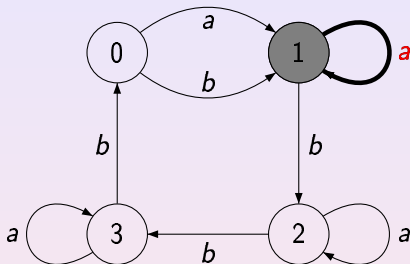
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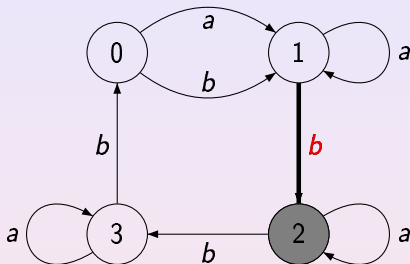


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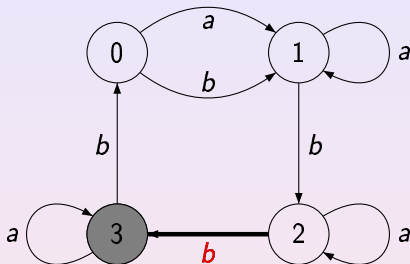
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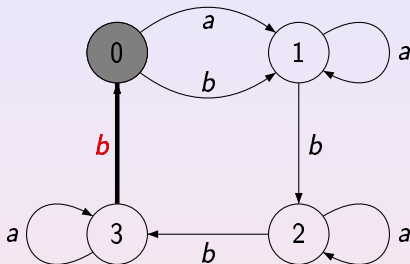


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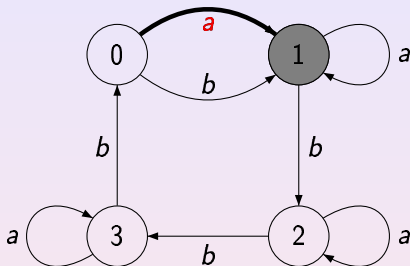
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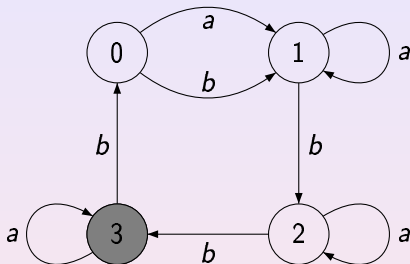
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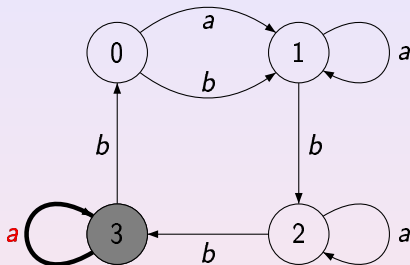
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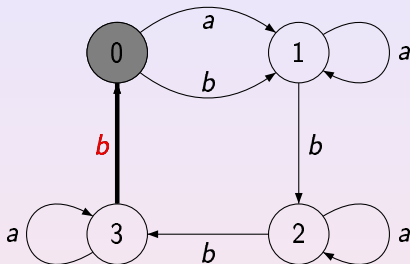
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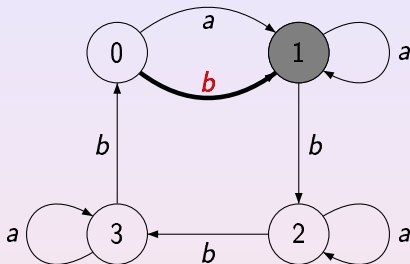


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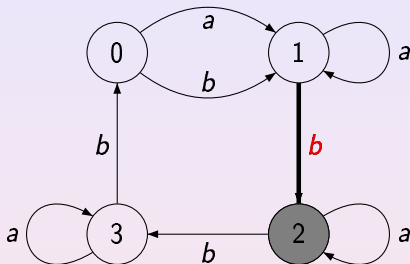
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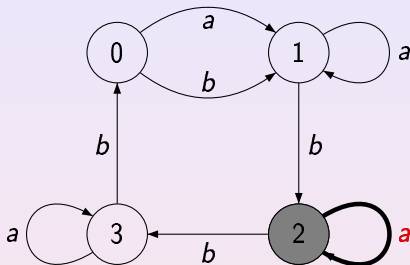
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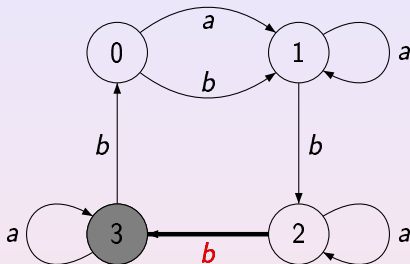
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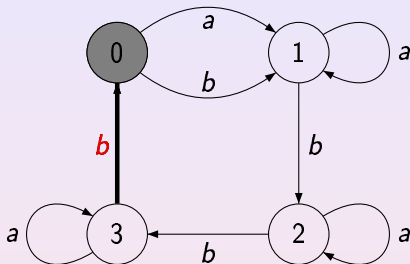
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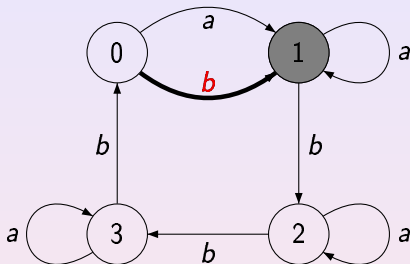
A reset word is $w = abbbabbba$: applying it at any state brings the automaton to the state 1.

$$0 \xrightarrow{w} 1$$
 


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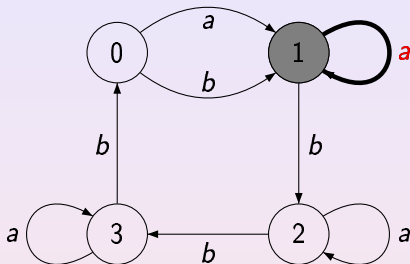
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GAIA, July 19, 2013

The notion was formalized in 1964 in a paper by Jan Černý (Poznámka k homogénnym experimentom s konečnými automatami, Matematicko-fyzikálny Časopis Slovensk. Akad. Vied, 14, no.3, 208–216 [in Slovak]) though implicitly it had been around since at least 1956.

The idea of synchronization is pretty natural and of obvious importance: we aim to restore control over a device whose current state is not known.

Think of a satellite which loops around the Moon and cannot be controlled from the Earth while “behind” the Moon (Černý's original motivation).

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A Frequently Discovered Notion

It is not surprising that synchronizing automata were re-invented a number of times:

- The notion was very natural by itself and fitted fairly well in what was considered as the mainstream of automata theory in the early 1960s.
- It also naturally arises in the framework of **variable-length codes** (such as Huffman codes), see, e.g., S. Even, “Test for synchronizability of finite automata and variable length codes”, IEEE Trans. Inform. Theory, 10 (1964), 185-189.
- Černý’s paper published in Slovak language remained unknown in the English-speaking world for quite a long time.

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Re-inventing by Engineers

In the 1980s, the notion was reinvented by engineers working in a branch of **robotics** which deals with part handling problems in industrial automation.

Suppose that one of the parts of a certain device has the following shape:



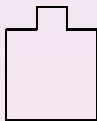
Such parts arrive at manufacturing sites in boxes and they need to be sorted and oriented before assembly.

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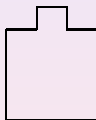
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Assume that only four initial orientations of the part shown above are possible, namely, the following ones:



Suppose that prior the assembly the part should take the “bump-left” orientation (the second one in the picture). Thus, one has to construct an orienter which action will put the part in the prescribed position independently of its initial orientation.

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Re-inventing by Engineers

We put parts to be oriented on a conveyer belt which takes them to the assembly point and let the stream of the parts encounter a series of passive obstacles of two types (**tall** and **low**) placed along the belt.

A tall obstacle is tall enough so that any part on the belt encounters this obstacle by its rightmost low angle.



Being carried by the belt, the part then is forced to turn 90° clockwise.

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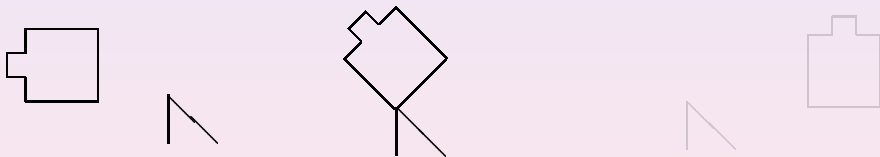
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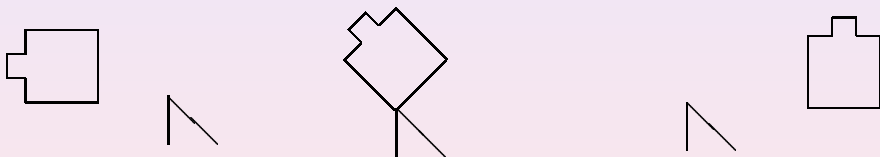
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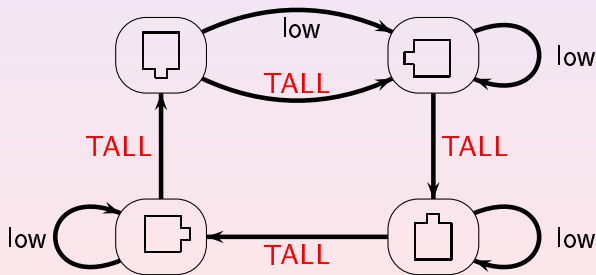
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A low obstacle has the same effect whenever the part is in the “bump-down” orientation; otherwise it does not touch the part which therefore passes by without changing the orientation.

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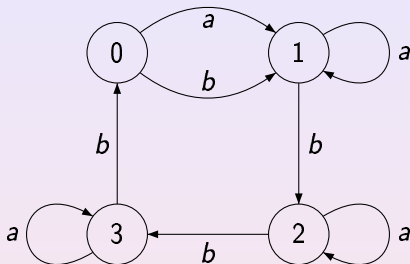
A low obstacle has the same effect whenever the part is in the “bump-down” orientation; otherwise it does not touch the part which therefore passes by without changing the orientation. The following schema summarizes how the obstacles effect the orientation of the part in question:



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We met this picture a few slides ago:



– this was our example of a synchronizing automaton, and we saw that *abbbabbba* is a reset sequence of actions. Hence the series of obstacles

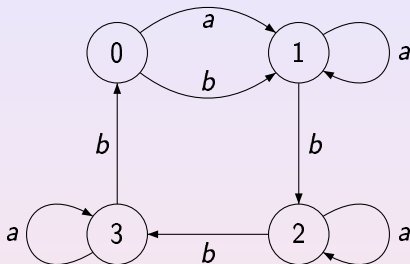
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Re-inventing by Dynamics Theorists

A **substitution** on a finite alphabet X is a map $\sigma : X \rightarrow X^+$; the substitution is said to be of **constant length** if all words $\sigma(x)$, $x \in X$, have the same length. One says that σ satisfies the **coincidence condition** if there exist positive integers m and k such that all words $\sigma^k(x)$ have the same letter in the m -th position. For an example, consider the substitution τ on $X = \{0, 1, 2\}$ defined by $0 \mapsto 11$, $1 \mapsto 12$, $2 \mapsto 20$. Calculate the iterations of τ up to τ^4 :

Thus, τ satisfies the coincidence condition (with $k = 4$, $m = 7$). The coincidence condition completely characterizes the constant length substitutions that give rise to dynamical systems measure-theoretically isomorphic to a translation on a compact Abelian group (Dekking, 1978).

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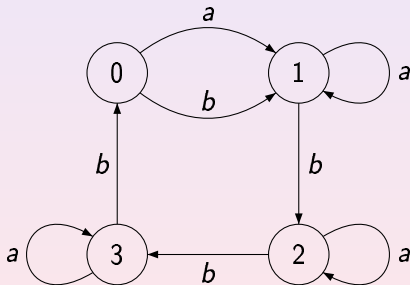
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There is a straightforward bijection between DFAs and constant length substitutions. Each DFA $\mathcal{A} = \langle Q, \Sigma, \delta \rangle$ with $\Sigma = \{a_1, \dots, a_\ell\}$ defines a length ℓ substitution on Q that maps every $q \in Q$ to the word $(q \cdot a_1) \dots (q \cdot a_\ell) \in Q^+$.

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induces the substitution $0 \mapsto 11$, $1 \mapsto 12$, $2 \mapsto 23$, $3 \mapsto 30$.

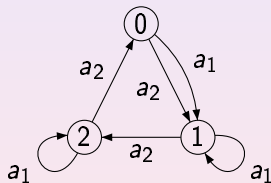
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Conversely, each substitution $\sigma : X \rightarrow X^+$ such that all words $\sigma(x)$, $x \in X$, have length ℓ gives rise to a DFA for which X is the state set and which has ℓ input letters a_1, \dots, a_ℓ acting on X as follows: $x \cdot a_i$ is the symbol in the i -th position of the word $\sigma(x)$.

Under this bijection substitutions satisfying the coincidence condition correspond precisely to synchronizing automata, and moreover, given a substitution, the step at which the coincidence first occurs is equal to the length of a shortest reset word for the corresponding automaton.

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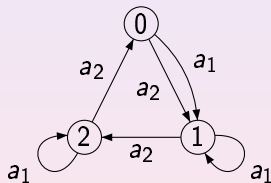


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Černý Conjecture

The **Černý conjecture** is the claim that every synchronizing automaton with n states possesses a reset word of length $(n - 1)^2$. The validity of the conjecture is the main open problem of the area and is arguably one of the most long-standing open problems in combinatorial theory of finite automata.

Define the *Černý function* $C(n)$ as the maximum length of shortest reset words for synchronizing automata with n states. In terms of this function, our current knowledge can be summarized in one line:

The Černý conjecture thus claims that in fact $C(n) = (n - 1)^2$.

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An Algebraic Viewpoint

One may treat DFAs as **unary algebras** since each letter of the input alphabet defines a unary operation on the state set.

Terms in the language of such unary algebras are expressions of the form $x \cdot w$, where x is a variable and w is a word over an alphabet Σ . Identities of unary algebras can be of the form either $x \cdot u = x \cdot v$ (**homotypical** identities) or $x \cdot u = y \cdot v$ with $x \neq y$ (**heterotypical** identities).

Clearly, if \mathcal{A} is a synchronizing automaton and w is its reset word, then \mathcal{A} satisfies the identity $x \cdot w = y \cdot w$. Conversely, if \mathcal{A} satisfies a heterotypical identity, $x \cdot u = y \cdot v$ say, then substituting y for x we get $y \cdot u = y \cdot v$ whence $x \cdot u = y \cdot u$. We conclude that u is a reset word for \mathcal{A} .

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Clearly, if \mathcal{A} is a synchronizing automaton and w is its reset word, then \mathcal{A} satisfies the identity $x \cdot w = y \cdot w$. Conversely, if \mathcal{A} satisfies a heterotypical identity, $x \cdot u = y \cdot v$ say, then substituting y for x we get $y \cdot u = y \cdot v$ whence $x \cdot u = y \cdot u$. We conclude that u is a reset word for \mathcal{A} .

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Thus, synchronizing automata = unary algebras satisfying heterotypical identities.

The Černý conjecture is thus just the claim that if a unary algebra on an n -element base set satisfies a heterotypical identity, then the algebra satisfies such an identity with one of the terms involved of length at most $(n - 1)^2$.

Disclaimers and applications ...

One real thing to remember: the Černý conjecture is a question about short identities in a certain algebra.

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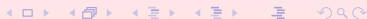
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Black-Box Version

Consider now a **black-box** synchronizing automaton $\mathcal{A} = \langle Q, \Sigma, ? \rangle$.
How to synchronize such an automaton?

Motivation: real computational devices are composites made from many finite automata, each with a relatively small number of states. We need an input signal which would simultaneously reset all those automata and which could be generated without analyzing the structure of each particular component of the device. In particular, Yacob Benenson *et al*'s "*soup of automata*", see "Programmable and autonomous computing machine made of biomolecules", *Nature* 414 (2001), 430–434; "DNA molecule provides a computing machine with both data and fuel", *Proc. National Acad. Sci. USA* 100 (2003), 2191–2196, is a solution containing 3×10^{12} DNA-based automata per μl that work in parallel on different inputs (DNA strands). One has to feed the automata with a common reset word in order to get them ready for a new use.

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Black-Box Version

Consider now a **black-box** synchronizing automaton $\mathcal{A} = \langle Q, \Sigma, ? \rangle$. (We know the state set and the input alphabet but we have no idea about the transition function.)

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Algebraic Applications

Universal reset words also admit various algebraic applications.

Reinhard Pöschel *et al* (“Identities in full transformation semigroups”, *Algebra Universalis* 31 (1994), 580–588) used them to find identities separating the full transformation semigroup \mathbb{T}_n from its proper subsemigroups;

Jorge Almeida and \sim (“Profinite identities for finite semigroups whose subgroups belong to a given pseudovariety”, *J. Algebra and its Applications* 2 (2003), 137–163) applied them to construct idempotents in the least ideal of the free profinite semigroup.

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Constructing Universal Reset Words

How to construct a universal reset word?

A brute force method relies on the fact that a synchronizing automaton with n states has a reset word of length at most $\frac{n^3-n}{6}$ (Pin-Frankl, 1983). Therefore, given a finite alphabet Σ , one can concatenate all words over Σ of length up to $\frac{n^3-n}{6}$ and get a word that resets all synchronizing automata with n states and input alphabet Σ . This idea is due to Masami Ito and Jürgen Duske “On cofinal and definite automata”, Acta Cybernetica 6 (1983), 181–189.

If the Černý conjecture holds true, it suffices to concatenate all words over Σ of length up to $(n-1)^2$. An accurate concatenation (based on the DeBruijn graph) yields a universal reset word of length $|\Sigma|^{(n-1)^2} + n^2 - 2n$.

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On the other hand, it is proved that such a word cannot have length less than $|\Sigma|^{n-1} + n - 2$.

Define the *universal Černý function* $UC(t, n)$ as the minimum length of a word that resets all synchronizing automata with n states and t input letters. In terms of this function, our current knowledge can be summarized in the following line:

$$t^{n-1} + n - 2 \leq UC(t, n) \leq t^{\frac{n^2-n}{2}} + o(t^{\frac{n^2-n}{2}}).$$

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$$t^{n-1} + n - 2 \leq UC(t, n) \leq t^{\frac{n^2-n}{2}} + o(t^{\frac{n^2-n}{2}}).$$

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Again, it should be clear that universal reset words correspond to heterotypical identities that hold in every unary algebra with given size of the base set.

Therefore, the problem of evaluating the universal Černý function $UC(t, n)$ is nothing but the problem of finding a heterotypical identity of minimum length which holds in all n -element algebras with t unary operations that satisfy a heterotypical identity.

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Separating Words by Automata

Let $\mathcal{A} = \langle Q, \Sigma, \delta \rangle$ be a DFA in which we fix an **initial** state $q_0 \in Q$ and a set of **final** states $F \subseteq Q$. We say that \mathcal{A} **accepts** a word $w \in \Sigma^*$ if $q_0 \cdot w \in F$, that is, the directed path starting at q_0 and labeled w ends at a state in F . Otherwise \mathcal{A} **rejects** w .

For instance, the above automaton accepts the word *aabb* but rejects the word *bbaa*.

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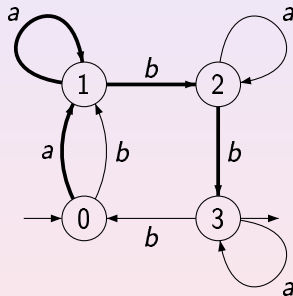
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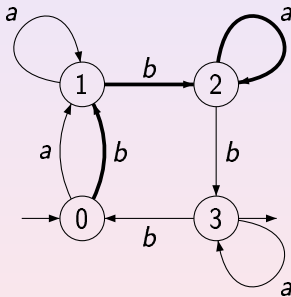


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Let $S(n) = \max \text{sep}(u, v)$ where u and v are distinct words of length at most n . The **Separating Words Problem** is to determine good upper and lower bounds on $S(n)$. It was introduced by Paweł Górałczik and Vačlav Koubek ("On discerning words by automata", Lect. Notes Comput. Sci. 226 (1986), 116–122), who proved

$$S(n) = o(n).$$

The best upper bound so far is due to Robson ("Separating words with machines and groups", RAIRO Inform. Théor. App., 30 (1996), 81–86), who obtained

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Algebraic Viewpoint

Observe that if distinct words u, v are such that the identity $u = v$ holds true in the full transformation semigroup \mathbb{T}_k , then u and v cannot be separated by any automaton $\mathcal{A} = \langle Q, \Sigma, \delta \rangle$ with at most k states. Indeed, the **transition semigroup** of \mathcal{A} , that is, the semigroup of transformations of the set Q induced by the words in Σ^* , embeds in \mathbb{T}_k whence u and v act the same on Q and are simultaneously accepted or rejected.

Hence short identities in \mathbb{T}_k may be used to produce lower bounds for the Separating Words Problem.

All known lower bounds for $S(n)$ are of magnitude $\Omega(\log n)$. They correspond to the following one-letter identity of \mathbb{T}_k :

$$x^{k-1} = x^{k-1+\text{lcm}(1,2,\dots,k)}.$$

It is known that $\text{lcm}(1, 2, \dots, k)$ grows faster than 2^k so that k is logarithmic in $\text{lcm}(1, 2, \dots, k)$.

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Identities in Symmetric Groups

A similar problem concerns separation of words by **permutation** automata (DFAs in which each letter acts as a permutation of the state set). Here the best upper bound so far is $O(n^{\frac{1}{2}})$ – this means that every two distinct words of length at most n can be separated by a permutation automaton with $O(n^{\frac{1}{2}})$ states – Robson, loc. cit. For a lower bound, one needs short “positive” identities in the symmetric group S_k .

Again, there is a one-letter identity of length $\text{lcm}(1, 2, \dots, k)$ which is exponential of k . However, at least for some k there are shorter identities, for instance, the identity

$$xxxyxyyyyyy = yyyyyyxyxx$$

of length 11 holds in S_4 while $\text{lcm}(1, 2, 3, 4) = 12$.

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New Identities in Symmetric Groups

Recent computational experiments have shown that the identity

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of length 32 holds in \mathbb{S}_5 while $\text{lcm}(1, 2, 3, 4, 5) = 60$.

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Observation: minimal length identities are **palindromic**.

Conclusion

Identities have been in focus of general algebra since its early days however it seems that algebraists (including myself) do not really care about **size** of identities.

Now we see that several popular and apparently hard questions in the theory of finite automata amount to ask for **short** identities in certain algebras.

I hope this fact may be interesting for algebraists and should stimulate a systematic study of shortest identities in various algebraic structures.

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